

Aachen, October 7-10, 2015



isual Computing







GCPR / VMV 2015

37th German Conference on Pattern Recognition

in conjunction with

20th International Symposium on Vision, Modeling and Visualization

October 7-10, 2015 Aachen, Germany

Hosted by:



In Cooperation with:

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Main Conference at a Glance

Wednesday, October 7th

12:00	Registration		
13:00 - 13:15	Opening		
13:15 - 14:15	Invited Talk: Niloy Mitra		
14:15 - 14:45	Coffee Break		
14:45 - 15:05	GCPR Opening + DAGM MVTec Award	VMV session 1: Geometry	
15:15 - 16:00	German Pattern Recognition Award		
16:00 - 16:15	Coffee Break		
16:00 - 18:00	Meeting of the GI Fachgruppe "Grafische	Datenverarbeitung"	
16:15 – 17:45	GCPR session 2: Motion and	VMV session 2: Visualization	
	Reconstruction		
18:00 - 19:30	DAGM Meeting		

Thursday, October 8th

08:30	Registration	
09:00 - 10:00	Invited Talk: Max Welling	
10:00 - 10:45	Plenary Oral session 1	
10:45 - 11:15	Coffee Break	
11:15 - 12:30	GCPR session 3: Math. Foundations & VMV session 3: Rendering	
	Image Processing	
12:30 - 13:30	Lunch	
13:30 - 15:00	GCPR session 4: Biomedical Image	VMV session 4: Images &
	Analysis & Applications	Video
15:00 - 17:00	Poster session 1 (with integrated Coffee	Break 15:00 – 15:30)
17:00 - 17:45	GCPR session 5: Human Pose Analysis	VMV session 5: Simulation
19:00 - 23:00	Conference Banquet (Coronation Hall, Aa	achen Town Hall)

Friday, October 9th

08:30	Registration	
09:00 - 10:00	Invited Talk: Andrew Blake	
10:00 - 10:45	Plenary Oral session 2	
10:45 - 11:15	Coffee Break	
11:15 – 12:30	GCPR session 6: Recognition & Scene VMV session 6: Acquisition	
_	Understanding	
12:30 - 13:30	Lunch	
13:30 - 15:30	Poster session 2 (with integrated Coffee Break 15:00 – 15:30)	
15:30 - 16:00	Closing & Awards	

Wednesday, October 7th

12:00 Registration

13:00 Opening

Keynote:

13:15 – 14:15

Niloy Mitra Room: Aula 2

Computational Design of Functional Objects Niloy Mitra (University College London)

Niloy Millia (Oniversity College Londo

Abstract

Both designers and novice users like to design functional objects for physical use. However, there exists limited computational support to facilitate this process. Existing tools either require specialized skills and extensive training, or force the users to perform extensive trial and error based exploration with limited guidance. In this talk we will discuss computational tools that support functional prototyping, guided designing, and material-aware modeling.

Short biography

Niloy J. Mitra leads the Smart Geometry Processing group in the Department of Computer Science at University College London (UCL). Niloy received his PhD degree from Stanford University under the guidance of Prof. Leonidas Guibas. His research interests include shape understanding, computational design, geometric processing, and more generally in computer graphics. Niloy received the ACM Siggraph Significant New Researcher Award in 2013 and the BCS Roger Needham Award in 2015.

14:15 Coffee Break

Wednesday, October 7th

14:45 GCPR Opening

15:00 DAGM MVTec Dissertation Award Ceremony

GCPR Oral Session 1:

15:15 - 16:00

German Pattern Recognition Award Talk

Room: AH V

German Pattern Recognition Award Talk To be announced

16:00	Coffee Break

GCPR Ora	l Session 2:	Motion and Reconstruction
16:15 – 1	7:45	Room: AH V
16:15	Road Condition Estimation based on Spatio-Ter Manuel Amthor, Bernd Hartmann, and Joachim	
16:37	Discrete Optimization for Optical Flow Moritz Menze, Christian Heipke, and Andreas Ge	eiger
17:00	Multi-Camera Structure from Motion with Eye- Sandro Esquivel and Reinhard Koch	to-Eye Calibration
17:22	Estimating Vehicle Ego-Motion and Piecewise P Optical Flow in a Continuous Framework Andreas Neufeld, Johannes Berger, Florian Becke Christoph Schnörr	-
18:00	DAGM Meeting	

14:45 VMV Opening

VMV Oral S	Session 1:	Geometry
14:50 – 16:00 Room: AH		Room: AH VI
14:50	Anisotropic Template Fitting for High Resolution Face Reconstr Jascha Achenbach, Eduard Zell, Mario Botsch	uction
15:12	Data Driven 3D Face Tracking Based on a Facial Deformation N Dominik Sibbing, Leif Kobbelt	1odel
15:35	Simple, robust, constant-time bounds on-surface geodesic dista point landmarks Oliver Burghard, Reinhard Klein	inces using
16:00	Coffee Break	
16:00	Meeting of the GI Fachgruppe "Grafische Datenverarbeitung" (E	3, room 118)
VMV Oral S	Session 2:	Visualization
16:15 – 17:	45	Room: AH VI
16:15	Temporal Coherence Predictor for Time Varying Volume Data B Perceptual Functions Tom Noonan, Lazaro Campoalegre, John Dingliana	lased on

- 16:37 Hierarchical Hashing for Pattern Search in 3D Vector Fields Zhongjie Wang, Hans-Peter Seidel, Tino Weinkauf
 - Interactive GPU-based Visualization of Scalar Data with Gaussian
- 17:00 Distributed Uncertainty

Steven Schlegel, Mathias Goldau, Gerik Scheuermann

A Taxonomy of Integration Techniques for Spatial and Non-Spatial

- Visualizations
- 17:22 Johannes Sorger, Thomas Ortner, Harald Piringer, Gerd Hesina, Eduard Gröller, Eduard

Thursday, October 8th

8:30 Registration

Invited Talk:

9:00 - 10:00

Max Welling Room: Aula 2

Learning to Generate

Max Welling (University of Amsterdam and University of California Irvine)

Abstract

The recent amazing success of deep learning has been mainly in discriminative learning, that is, classification and regression. An important factor for this success has been, besides Moore's law, the availability of large labeled datasets. However, it is not clear whether in the future the amount of available labels grows as fast as the amount of unlabeled data, providing one argument to be interested in unsupervised and semi-supervised learning. Besides this there are a number of other reasons why unsupervised learning is still important, such as the fact that data in the life sciences often has many more features than instances (p>n), the fact that probabilities over feature space are useful for planning and control problems and the fact that complex simulator models are the norm in the sciences. In this talk I will discuss deep generative models that can be jointly trained with discriminative models and that facilitate semi-supervised learning. I will discuss recent progress in learning and Bayesian inference in these "variational auto-encoders". I will then extend the deep generative models to the class of simulators for which no tractable likelihood exists and discuss new Bayesian inference procedures to fit these models to data.

Short biography

Max Welling is a Professor of Computer Science at the University of Amsterdam and the University of California Irvine. In the past he held postdoctoral positions at Caltech ('98-'00), UCL ('00-'01) and the U. Toronto ('01-'03). He received his PhD in '98 under supervision of Nobel laureate Prof. G. 't Hooft.

Max Welling served as associate editor in chief of IEEE TPAMI from 2011-2015. He serves on the editorial boards of JMLR and JML and was an associate editor for Neurocomputing, JCGS and TPAMI. In 2009 he was conference chair for AISTATS, in 2013 he was be program chair for NIPS, in 2014 he was the general chair for NIPS and in 2016 he will be a program chair at ECCV. He received multiple grants from NSF, NIH, ONR, NWO, Facebook, Yahoo and Google, among which an NSF career grant in 2005. He is recipient of the ECCV Koenderink Prize in 2010 and the best paper award at ICML 2012.

Welling is currently the director of the master program in artificial intelligence at the UvA and he is in the scientific board of the newly opened Data Science Research Center in Amsterdam. He is also an associate fellow of the Neural Computation and Adaptive Perception Program at the Canadian Institute for Advanced Research. Welling's research focuses on large-scale statistical learning. He has made contributions in Bayesian learning, approximate inference in graphical models and visual object recognition. He has over 150 academic publications.

Plenary (Dral Session 1:
10:00 – 10:45 Room: A	
10:00	Point-wise Map Recovery and Refinement from Functional Correspondence (VMV) Emanuele Rodola, Michael Moeller, Daniel Cremers
10:22	<i>Efficient Two-View Geometry Classification (GCPR)</i> Johannes L. Schönberger, Alexander C. Berg, and Jan-Michael Frahm
10.42	Coffee Break

Thursday, October 8th

GCPR Or	al Session 3:	Mathematical Foundations and Image Processing
11:15 – 1	12:30	Room: AH V
11:15		proach to the Affine Subspace Clustering Problem ard Reinelt, and Christoph Schnörr
11:37	-	hisotropy into Second Order Coupling Models er Schroers, and Joachim Weickert
12:00		<i>d Deconvolution for Document Image Restoration</i> Maier, and Vincent Christlein
12:30	Lunch (Aula 2)	
	al Session 4:	Biomedical Image Analysis and Applications
13:30 – 1	15:00	Room: AH V
13:30	Unsupervised and Accur Images Niklas Mevenkamp and I	rate Extraction of Primitive Unit Cells from Crystal Benjamin Berkels
13:52	Copula Archetypal Anal Dinu Kaufmann, Sebastia	ysis an Keller, and Volker Roth
14:15	-	eval for Biodiversity Research a Schadt, and Joachim Denzler
14:37	Temporal Acoustic Word Rene Grzeszick, Axel Plin	ds for Online Acoustic Event Detection age, and Gernot A. Fink
15:00	Coffee Break	

VMV Oral	Session 3:	Rendering
11:15 – 12	2:30	Room: AH VI
11:15	Vector-to-Closest-Point Octree for Surface Ray-Casting Ismail Demir, Rüdiger Westermann	
11:37	Level-of-Detail for Production-Scale Path Tracing Magdalena Prus, Christian Eisenacher, Marc Stamminger	
12:00	The Bounced Z-buffer for Indirect Visibility Oliver Nalbach, Tobias Ritschel, Hans-Peter Seidel	
12:30	Lunch (Aula 2)	
		ages and Video
13:30 – 15	:00	Room: AH VI
13:30	A Convex Clustering-based Regularizer for Image Segmentati Benjamin Hell, Markus Magnor	
13:30 13:52		on
	Benjamin Hell, Markus Magnor Temporally Consistent Wide Baseline Facial Performance Cap Warping	on ture via Image ng

15:00 Coffee Break

Thursday, October 8th

Poster Session 1, Young Researchers Forum, and Nectar Track

15:00 - 17:00

1	Line3D: Efficient 3D Scene Abstraction for the Built Environment Manuel Hofer, Michael Maurer, and Horst Bischof
2	An Efficient Linearisation Approach for Variational Perspective Shape From Shading Daniel Maurer, Yong Chul Ju, Michael Breuß, and Andrés Bruhn
3	TomoGC: Binary Tomography by Constrained GraphCuts Jörg Hendrik Kappes, Stefania Petra, Christoph Schnörr, and Matthias Zisler
4	An Improved Eikonal Method for Surface Normal Integration Martin Baehr and Michael Breuß
5	Fast Techniques for Monocular Visual Odometry M. Hossein Mirabdollah and Bärbel Mertsching
6	<i>Iterative Automated Foreground Segmentation in Video Sequences Using</i> <i>Graph Cuts</i> Tomislav Hrkać and Karla Brkić
7	A Parametric Spectral Model for Texture-Based Salience Kasim Terzić, Sai Krishna, and J.M.H. du Buf
8	High Speed Lossless Image Compression Hendrik Siedelmann, Alexander Wender, and Martin Fuchs
9	Learning Reaction-Diffusion Models for Image Inpainting Wei Yu, Stefan Heber, and Thomas Pock
10	Image Orientation Estimation with Convolutional Networks Philipp Fischer, Alexey Dosovitskiy, and Thomas Brox
11	Semi-Automatic Basket Catheter Reconstruction from two X-ray views Xia Zhong, Matthias Hoffmann, Norbert Strobel, and Andreas Maier

16

Fast Brain MRI Registration with Automatic Landmark Detection Using a Single Template Image Olga V. Senyukova and Denis S. Zobnin

Photorealistic Face Transfer in 2D and 3D Video Daniel Merget, Philipp Tiefenbacher, Mohammadreza Babaee, Nikola Mitov, and Gerhard Rigoll

Young Researcher Forum Posters

YRF1	Random Forests for 3D Pose Estimation from 2D Images
INFI	Ilya Kostrikov

YRF2 Image Segmentation in Twenty Questions Christian Rupprecht

Nectar Track Posters

Discovering Object Classes from Activities

NT1 Abhilash Srikanta, Jürgen Gall (ECCV 2014)

Stereo Ground Truth with Error Bars

NT2 Daniel Kondermann, Rahul Nair, Stephan Meister, Wolfgang Mischler, Burkhard Güssefeld, Claus Brenner, Bernd Jähne (ACCV 2014)

Visualizing Tensor Normal Distributions at Multiple Levels of Detail

NT3 A. Abbasloo, V. Wiens, M. Hermann, T. Schultz (TVCG / IEEE VIS 2015)

Learning Analysis-by-Synthesis for 6D Pose Estimation in RGB-D Images

Carsten Rother (ICCV 2015)

NT4

	Selecting Influential Examples: Active Learning with Expected Model Output
NT5	Changes
	Alexander Freytag, Erik Rodner, and Joachim Denzler
	(ECCV 2014)

NT6	Traditional Saliency Reloaded: A Good Old Model in New Shape Simone Frintrop, Thomas Werner, and Germán Martín García (CVPR 2015)
NT7	Material Classification based on Training Data Synthesized Using a BTF Database Michael Weinmann, Juergen Gall, Reinhard Klein (ECCV'14)
NT8	Driven Learning for Driving: How Introspection Improves Semantic Mapping R. Triebel, H. Grimmet, R. Paul, I. Posner (ISRR 2013)
NT9	Face detection without bells and whistles Markus Mathias, Rodrigo Benenson, Marco Pedersoli, Luc Van Gool (ECCV 2014)
NT10	Linguistic Knowledge for Visual Recognition and Natural Language Descriptions of Visual Content Marcus Rohrbach (DAGM MVTec Dissertation Award)

Thursday, October 8th		
GCPR Ora	GCPR Oral Session 5: Human Pose Analysis	
17:00 – 17:45 Room		Room: AH V
17:00	Biternion Nets: Continuous Head Pose Regression fr Labels Lucas Beyer, Alexander Hermans, and Bastian Leibe	om Discrete Training
17:22	A physics-based statistical model for human gait and Petrissa Zell and Bodo Rosenhahn	alysis
19:00	Conference Banquet (Coronation Hall, Aachen Town Hall)	

VMV Ora	I Session 5:	Simulation
17:00 – 1	7:45	Room: AH VI
17:00	Tongue S(t)imulator - A Comprehensive Parametrized Pose N Speech Therapy Laura Haraké, Dorota Beltkiewicz, Gerrit Lochmann	1odel for
17:22	Simulation of Water Condensation based on a Thermodynan using Implicit Surfaces Sebastian-Torsten Tillmann, Christian-Arved Bohn	nic Approach
19:00	Conference Banquet	
	(Coronation Hall, Aachen Town Hall)	

Friday, October 9th

8:30 Registration

Keynote

9:00 - 10:00

Room: Aula 2

Analysis by Synthesis versus Learned Detection for Vision Andrew Blake (Microsoft Research Cambridge)

Abstract

Machine vision works nowadays. Machines can: navigate using vision; separate object from background; recognise a wide variety of objects, and often track their motion. These abilities are great spin-offs in their own right, but are also part of an extended adventure in understanding the nature of intelligence through vision.

One question is whether intelligent systems will turn out to depend more on generative models, or on networks trained on data at ever greater scale? In vision systems this boils down to the roles of two paradigms: analysis-by-synthesis versus empirical recognisers. Each approach has its strengths, and empirical recognisers especially have made great strides in performance in the last few years, through deep learning. One can speculate about how deeply the two approaches may eventually be integrated, and on the progress that has already been made with such integration.

Short biography

Andrew Blake is a Microsoft Distinguished Scientist and the Laboratory Director of Microsoft Research Cambridge, England. He joined Microsoft in 1999 as a Senior Researcher to found the Computer Vision group. In 2008 he became a Deputy Managing Director at the lab, before assuming his current position in 2010. Prior to joining Microsoft Andrew trained in mathematics and electrical engineering in Cambridge England, and studied for a doctorate in Artificial Intelligence in Edinburgh. He was an academic for 18 years, latterly on the faculty at Oxford University, where he was a pioneer in the development of the theory and algorithms that can make it possible for computers to behave as seeing machines.

He has published several books including "Visual Reconstruction" with

A.Zisserman (MIT press), "Active Vision" with A. Yuille (MIT Press) and "Active Contours" with M. Isard (Springer-Verlag). He has twice won the prize of the European Conference on Computer Vision, with R. Cipolla in 1992 and with M. Isard in 1996, and was awarded the IEEE David Marr Prize (jointly with K. Toyama) in 2001.

In 2006 the Royal Academy of Engineering awarded him its Silver Medal and in 2007 the Institution of Engineering and Technology presented him with the Mountbatten Medal (previously awarded to computer pioneers Maurice Wilkes and Tim Berners-Lee, amongst others). He was elected Fellow of the in 1998, Fellow of the IEEE in 2008, and Fellow of the Royal Society in 2005. In 2010, Andrew was elected to the council of the Royal Society. In 2011, he and colleagues at Microsoft Research received the Royal Academy of Engineering MacRobert Award for their machine learning contribution to Microsoft Kinect human motion-capture. In 2012 Andrew was elected to the board of the EPSRC and also received an honorary degree of Doctor of Science from the University of Edinburgh. In 2013 Andrew was awarded an honorary degree of Doctor of Engineering from the University of Sheffield. In 2014, Andrew gave the prestigious Gibbs lecture at the Joint Mathematics Meetings.

Plenary Oral Session 2:

10:45

10:00 - 10:45Room: Aula 2 Joint 3D Object and Layout Inference from a single RGB-D Image (GCPR) 10:00 Andreas Geiger and Chaohui Wang Variational Separation of Light Field Layers (VMV) 10:23 Ole Johannsen, Antonin Sulc, Bastian Goldluecke Coffee Break

Friday, September 5th

GCPR Ora	l Session 6:	Recognition and Scene Understanding
11:15 – 12:30 Room:		Room: AH V
11:15	Object Proposals Estimation in Singl Shape Manifolds Shuai Zheng, Victor Adrian Prisacariu Niloy J. Mitra, Jamie Shotton, Philip H	, Melinos Averkiou, Ming-Ming Cheng,
11:40	The Long-Short Story of Movie Desc Anna Rohrbach, Marcus Rohrbach, a	•
12:05	Graph-Based Deformable 3D Object Bertram Drost and Slobodan Ilic	Matching

12:30	Lunch			

VMV Oral S	ession 6:	Acquisition
11:15 - 12:	30	Room: AH VI
11:15	Extrapolating Large-Scale Material BTFs under Cross-Device Co Heinz Christian Steinhausen, Dennis den Brok, Matthias Hullin, F	
11:40	Fast multiplexed acquisition of material reflectance Dennis den Brok, Heinz-Christian Steinhausen, Reinhard Klein	
12:05	Light Field Imaging through Household Optics Alexander Wender, Julian Iseringhausen, Bastian Goldluecke, Ma Matthias Hullin	artin Fuchs,

	12:30	Lunch					
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Friday, September 5th

Poster Sess	ion 2, Young Researchers Forum, and Nectar Track
13:30 - 15:3	30
14	GraphFlow - 6D Large Displacement Scene Flow via Graph Matching Hassan Abu Alhaija, Anita Sellent, Daniel Kondermann, and Carsten Rother
15	FlowCap: 2D Human Pose from Optical Flow Javier Romero, Matthew Loper, and Michael J. Black
16	3D Facial Landmark Detection: How to Deal with Head Rotations? Anke Schwarz, Esther-Sabrina Wacker, Manuel Martin, M. Saquib Sarfraz, and Rainer Stiefelhagen
17	Enhanced GPT Correlation for 2D Projection Transformation Invariant Template Matching Toru Wakahara and Yukihiko Yamashita
18	Semantic segmentation based traffic light detection at day and at night. Vladimir Haltakov, Jakob Mayr, Christian Unger, and Slobodan Ilic
19	Pose Estimation and Shape Retrieval with Hough Voting in a Continuous Voting Space Viktor Seib, Norman Link, and Dietrich Paulus
20	Fast Approximate GMM Soft-Assign for Fine-Grained Image Classification with Large Fisher Vectors Josip Krapac and Siniša Šegvić
21	Regressor Based Estimation of The Eye Pupil Center Necmeddin Said Karakoc, Samil Karahan, and Yusuf Sinan Akgul
22	Patch-level Spatial Layout for Classification and Weakly Supervised Localization Valentina Zadrija, Josip Krapac, Jakob Verbeek, and Siniša Šegvić
	A Deeper Look at Dataset Bias

23 Tatiana Tommasi, Novi Patricia, Barbara Caputo, and Tinne Tuytelaars

24	What is Holding Back Convnets for Detection?
24	Bojan Pepik, Rodrigo Benenson, Tobias Ritschel, and Bernt Schiele
25	A Modified Isomap Approach to Manifold Learning in Word Spotting
25	Sebastian Sudholt and Gernot A. Fink
	Offline Writer Identification Using Convolutional Neural Network Activation
26	Features
	Vincent Christlein, David Bernecker, Andreas Maier, and Elli Angelopoulou

Young Researchers Forum Posters

	Implicit-to-Implicit Registration for Real-Time 3D Reconstruction from RGB-
YRF3	D Data
	Miroslava Slavcheva
YRF4	Superpixel Segmentation: An Evaluation
	David Stutz

YRF5 Robot Arm Tracking with Random Decision Forests Felix Widmaier

Nectar Track Posters

	U-Net: Convolutional Networks for Biomedical Image Segmentation
NT11	Olaf Ronneberger, Philipp Fischer, Thomas Brox
	(MICCAI 2015)

Active Learning and Discovery of Object Categories in the Presence of Unnameable Instances NT12 Christoph Käding, Alexander Freytag, Erik Rodner, Paul Bodesheim, Joachim Denzler (CVPR 2015)

NT13 Ask Your Neurons: A Neural-based Approach to Answering Questions about Images Mateusz Malinowski, Marcus Rohrbach, Mario Fritz (ICCV 2015)

	(3DV 2014)
	Human Pose Estimation with Fields of Parts
NT15	Martin Kiefel, Peter Gehler
	(ECCV 2014)
	The Language of Actions: Recovering the Syntax and Semantics of Goal-
NT16	Directed Human Activities
	Hilde Kuehne, Ali Arslan, Thomas Serre
	Expanding Object Detector's Horizon: Incremental Learning Framework for
NT17	Object Detection in Videos
NI17	Alina Kuznetsova, Sung Ju Hwang, Bodo Rosenhahn, Leonid Sigal
	(CVPR 2015)
	Extended Pie Menus for Immersive Virtual Environments
NT18	S. Gebhardt, S. Pick, F. Leithold, B. Hentschel, T.W. Kuhlen
	(IEEE TVCG 2013)
	Dyna: A Model of Dynamic Human Shape in Motion
NT19	G. Pons-Moll, J. Romero, N. Mahmood, M.J. Black
	(SIGGRAPH 2015)
	Efficient Dense Rigid-Body Motion Segmentation and Estimation in RGB-D
NT20	Video
	Jörg Stückler, Sven Behnke
	(IJCV 2015)
15:00	Coffee Break

15:30 Awards and Closing

Tutorials/Workshop at a Glance

Saturday, October 10th

08:30	Registration
09:00 - 12:30	Tutorial: Causality (Part 1)
09:00 - 12:30	Workshop: New Challenges in Neural Computation and Machine Learning
12:30 - 13:30	Lunch (Restaurant Lara)
13:30 - 17:00	Tutorial: Causality (Part 2)
14:00 - 17:45	Workshop: New Challenges in Neural Computation and Machine Learning

Saturday, October 10th

8:30 Registration

Tutorial:

9:00 - 17:00

Causality

Room: AH VI

Causality

Jonas Peters (Max Planck Institute for Intelligent Systems, Tübingen)

Abstract

In the field of causality we are interested in answering questions like how a system reacts under interventions (e.g. in gene knock-out experiments). These questions go beyond statistical dependencies and can therefore not be answered by standard regression or classification techniques. While humans are very efficient in learning causal relations between few random variables, we require automated procedures in situations where many and/or high-dimensional data are available.

In this tutorial you will learn about the interesting problem of causal inference and recent developments in the field. The tutorial does not require any prior knowledge about causality.

Part 1: We introduce structural equation models and formalize interventional distributions. We define causal effects and show how to compute them if the causal structure is known.

Part 2: We present three ideas that can be used to infer causal structure from data: (1) finding (conditional) independences in the data, (2) restricting structural equation models and (3) exploiting the fact that causal models remain invariant in different environments.

Part 3: If time allows, we show how causal concepts can be applied in the field of machine learning.

Workshop:	New Challenges in Neural Computation (NC2)				
	Room: AH V				
09:00	Opening				
Oral Sessio	n 1 Representation Learning				
9:00 - 09:5	0				
	Archetypal Analysis as an Autoencoder				
9:00	Christian Bauckhage, Kristian Kersting, Florian Hoppe, Christian Thurau				
0.10	Learning Transformation Invariance from Global to Local				
9:10	Jens Hocke, Thomas Martinetz				
9:20	Polynomial approximation of spectral data in LVQ and Relevance Learning				
9.20	Friedrich Melchert, Michael Biehl				
9:30	Dissimilarity Extraction in a Median Variant of Learning Vector Quantization				
9.30	David Nebel, Marika Kaden				
9:40	Towards Dimensionality Reduction for Smart Home Sensor Data				
5.40	Bassam Mokbel, Alexander Schulz				
Oral Sessio	n 2 Time Series and Sensor Streams				
9:50 - 10:4	0				
	Impact of Regularization on the Model Space for Time Series Classification				
9:50	Witali Aswolinskiy, René Felix Reinhart, Jochen Steil				
	Ensembles of Neural Oscillators				
10:00	Danil Koryakin, Fabian Schrodt, Martin V. Butz				
	Ensemble Methods and Active Learning in HCI				
10:10	Patrick Thiam, Markus Kächele, Friedhelm Schwenker, Günther Palm				
	Predictable Feature Analysis				
10:20	Stefan Richthofer, Laurenz Wiskott				
	Incremental learning of action models as HMMs over qualitative trajectory				
10:30	representations				
	Maximilian Panzner, Philipp Cimiano				

Saturday, October 10th

10:40 Coffee Break

Poster Session

10:40 - 11:40

All talks from Oral Sessions 1 and 2 have a poster here.

Joschka Boedecker

Invited Talk

11:40 - 12:30

Representation Learning for Control

Joschka Boedecker (University of Freiburg)

12:30	Lunch (Restaurant Lara)			
Oral Session 3 Deep Learning				
13:30 – 15:10				
13:30	On the Applicability of Recurrent Neural Networks for Pattern Recognition in Electroencephalography Signals Marcel Binz, Sebastian Otte, Andreas Zell			
13:40	Population Monte Carlo Meets Contrastive Divergence Learning Oswin Krause, Asja Fischer, Christian Igel			
13:50	CAPTCHA Recognition with Active Deep Learning Fabian Stark, Caner Hazırbaş, Rudolph Triebel, Daniel Cremers			
14:00	Intrinsic Plasticity: A Simple Mechanism to Stabilize Hebbian Learning in Multilayer Neural Networks Michael Teichmann, Fred H. Hamker			
14:10	<i>Identifying bank stress by deep learning of news</i> Samuel Rönnqvist, Peter Sarlin			

Oral Session	n 4 Dimensionality Reduction & Information Transfer					
13:30 - 15:10						
14:20	<i>Visualisation of heterogeneous data with simultaneous feature saliency using Generalised Generative Topographic Mapping</i> Shahzad Mumtaz, Michel F. Randrianandrasana, Gurjinder Bassi, Ian T. Nabney					
14:30	Incremental Class Learning and Novel Class Detection of Gestures Using Ensemble Husam Al-Behadili, Arne Grumpe, Christian Dopp, Christian Wöhler					
14:40	Attention as cognitive, holistic control of the visual system Frederik Beuth, Fred H. Hamker					
14:50	Learning Conditional Mappings between Population-Coded Modalities Fabian Schrodt, Martin V. Butz					
15:00	Nyström approximation toolbox Andrej Gisbrecht and Frank-Michael Schleif					
15:10	Coffee Break					

Poster Session 2

15:10 - 16:10

All talks from Oral Sessions 3 and 4 have a poster here.

Invited Talk:

16:10 - 17:00

Christian Igel

Deep Learning and Medical Image Analysis Christian Igel (University of Kopenhagen)

17:00 Awards and Closing

17:10	Meeting of the GI Fachgruppe Neural Networks	
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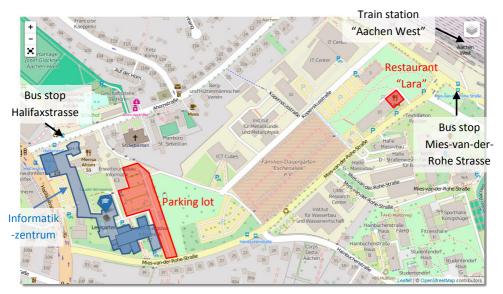
Notes

Notes

Additional Information: Conference Location

Directions:

- The conference takes place in RWTH Aachen University's "Informatikzentrum".
- Arrival by bus: The conference location is conveniently reachable with bus line 33 (direction "Uniklinik/Vaals", bus stop "Halifaxstrasse" directly in front of the building) and bus line 3A (direction "Uniklinik", bus stop "Mies-van-der-Rohe Strasse", 300m walk from there). Both bus lines pass through the inner city and are easily reachable from most hotels.
- Arrival by train: The closest train station is "Aachen West", 2 stations from "Aachen Hauptbahnhof". Many trains stop here, so this is a very convenient and fast way to reach the conference from the Hauptbahnhof area. After arriving at "Aachen West", leave the platform, go downstairs to the underpass and turn right into Seffenter Weg; turn left into Mies-van-der-Rohe-Straße and go straight uphill until you reach the Informatikzentrum.
- Arrival by taxi: The address of the conference location is "Informatikzentrum, Ahornstrasse 55".
- Arrival with an own car: The Informatikzentrum has an own parking lot with an entry on Mies-van-der-Rohe Strasse. Parking there requires a parking ticket, which you can get at the registration desk. Please get your parking ticket directly after your arrival and put it into your car.



Lunch breaks:

- For early arrivals on Wednesday, there will be some fingerfood at the conference in front of Aula2.
- On Thursday and Friday, there will be a catered lunch served from 12:30 13:30 in Aula2 (included in the conference registration).
- For the workshop and tutorial on Saturday, lunch arrangements have been made at restaurant "Lara", Mies-van-der-Rohe Strasse 10 (included for NC2 participants).

WiFi access:

 Connect to "mops" Login: gcprvmv2015 Password: tugebub



Conference banquet:

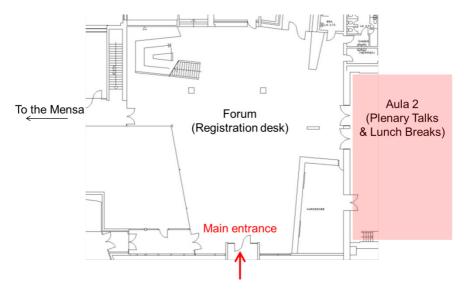
- The conference banquet will take place in the Coronation Hall of Aachen's historic Town Hall building on Market Square (see big map on p.39). The Town Hall is one of Aachen's main landmark buildings, located vis-à-vis the Cathedral. Parts of the building date back to the reign of Charlemagne (800 AD).
- Entry will be on Thursday evening at 19:00h and the dinner will start at around 19:30h.

Maps of the conference location:

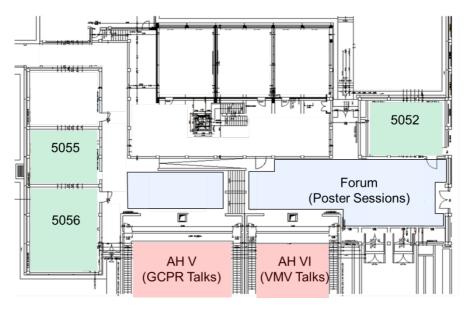
 The keynotes and plenary sessions of both conferences will take place jointly in "Aula2", while the main conference talks will take place in parallel in lecture halls AH V (GCPR) and AH VI (VMV), respectively.



Keynote and plenary talks, lunch breaks:



Main conference talks and poster sessions:





Map by OpenStreetMap

Conference Program at a Glance

Time	Wed, 07.10.		Thu, 08.10.		Fri, 09.10.		Sat, 10.10.	
	GCPR	VMV	GCPR	VMV	GCPR	VMV	Tutorial Causality	NC2 Workshop
8:30			Registration		Registration		Registration	
9:00								
9:30			Keynote: M	ax Welling	Keynote: Andrew Blake		Part 1a Causal Language	Oral Sessions
10:00			Plenary Oral	Session 1	Plenary Oral Session 2			
10:30			Coff		Coffee		Coffee	
11:00			Coll	66				Posters
11:30			Oral Session 3	Oral Session 3	Oral Session 6 Recognition &	Oral Session 6	Part 1b Causal Reasoning	Invited Talk:
12:00			Math. Foundations & Img. Processing	Rendering	Scene Under- standing	Acquisition	outourrouconing	Joschka Boedecker
12:30	Regist	ration						
13:00	Opening		Lunch (Aula 2)		Lunch (Aula 2)		Lunch (Restaurant Lara)	
13:30	Keynote: Niloy Mitra							
14:00	Keynote. I	anoy mina	Oral Session 4 Oral Session 4 Biomedical Image				Part 2	Oral Sessions
14:30	Coffee		Analysis and Applications	Images and Video	Poster Session 2		Causal Discovery	Oral Sessions
	GCPR Opening							
15:00	German Pattern Recognition Award	Oral Session 1	Coff	ee	Cof	fee	Coff	ee
15:30	Talk	Geometry			Closing & Awards			Posters
16:00	Cof	fee	Poster Se	ession 1			Part 3 Applications	location of Tables
16:30	Oral Session 2	Oral Session 2						Invited Talk: Christian Igel
17:00	Motion and Reconstruction	Visualization	Oral Session 5	Oral Session 5				
17:30	Reconstruction		Human Pose Analysis	Simulation				Meeting of the GI Fachgruppe
18:00								Neural Networks
18:30								
19:00	DAGM Meeting						Room Le	egend:
19:30			Conference	o Dinnor			Aula 2 (Plenary Sessions)	
20:00			Conference Dinner (Coronation Hall, Aachen Town Hall) 19:00 - 23:00				AH V (GCPR)	AH VI (Tutorial)
							AH VI	AHV
20:30							(VMV)	(NC2 Workshop)